6ES7510-1DK03-0AB0

Data sheet



SIMATIC DP, CPU 1510SP-1 PN for ET 200SP, central processing unit with work memory 200 KB for program and 1 MB for data, 1st interface: PROFINET IRT with 3-port switch, 25 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

Product type designation HW functional status FS04 Firmware version • FW update possible Product function • I&M data • Module swapping during operation (hot swapping) • Isochronous mode • SysLog Engineering with • STEP 7 TIA Portal configurable/integrated from version via dataset Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Rains Voltage failure stored energy time • Mains Voltage failure stored energy time PS04 Y4.0 Y4.0 Y4.0 Yes; I&M0 to I&M3 Yes; Multi-hot swapping Yes; M
Firmware version Firmwa
FW update possible Product function
Product function I &M data Module swapping during operation (hot swapping) I sochronous mode SysLog Engineering with STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control via dataset Yes Control elements Mode selector switch A supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
I&M data
Module swapping during operation (hot swapping) Isochronous mode SysLog Yes Engineering with STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control Via dataset Yes Control elements Mode selector switch Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering Yes; Multi-hot swapping Y
Isochronous mode SysLog Yes Engineering with STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
SysLog Engineering with STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
Engineering with STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
STEP 7 TIA Portal configurable/integrated from version V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0 Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) permissible range, upper limit (DC) Reverse polarity protection Yes Mains buffering
versions as 6ÉS7510-1DJ01-0ÁB0 Configuration control via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
via dataset Yes Control elements Mode selector switch 1 Supply voltage Rated value (DC) 24 V permissible range, lower limit (DC) 19.2 V permissible range, upper limit (DC) 28.8 V Reverse polarity protection Yes Mains buffering
Mode selector switch Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
Mode selector switch Supply voltage Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Yes Mains buffering
Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
Rated value (DC) permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection Mains buffering
permissible range, upper limit (DC) Reverse polarity protection Mains buffering 28.8 V Yes
Reverse polarity protection Yes Mains buffering
Mains buffering
Mains/voltage failure stored energy time 10 ms
•
Input current
Current consumption (rated value) 0.48 A
Current consumption, max. 0.7 A
Inrush current, max. 1.34 A; Rated value
0.3 A ² ·s
Power
Infeed power to the backplane bus 8.05 W
Power loss
Power loss, typ. 3.5 W
Memory
Number of slots for SIMATIC memory card 1
SIMATIC memory card required Yes
Work memory
• integrated (for program) 200 kbyte
• integrated (for data) 1 Mbyte
Load memory

 Plug-in (SIMATIC Memory Card), max. 	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	1 Mbyte, 1 of bbs with absolute addressing, the max. Size is 64 Nb
Number range	0 65 535
• Size, max.	200 kbyte
FC	
Number range	0 65 535
• Size, max.	200 kbyte
ОВ	
• Size, max.	200 kbyte
Number of free cycle OBs	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 µs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	2010
— adjustable	Yes
IEC counter	100
Number	Any (only limited by the main memory)
Retentivity	, ()
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	, , , , , , , , , , , , , , , , , , , ,
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes

Retentivity preset	No
Retentivity preset Local data	INO
	64 khyto: may 16 KP par block
per priority class, max. Address area	64 kbyte; max. 16 KB per block
	0.040. many growth and formativities (submandivities
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	A.V
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	·
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Address space per module	
Address space per module, max.	288 byte; For input and output data respectively
Address space per station	
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2 048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	
Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
 Quantity of operable ET 200SP modules, max. 	64
 Quantity of operable ET 200AL modules, max. 	16
 Number of lines, max. 	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	. ,
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, master	Yes
₹ III AO, UEVICE	100
on Ethernet via NTD	Vac
on Ethernet via NTP Interfaces	Yes
Interfaces	
Interfaces Number of PROFINET interfaces	1
Number of PROFIBUS interfaces Number of PROFIBUS interfaces	1 1; Via CM DP module
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface	1
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface	1 1; Via CM DP module
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types • RJ 45 (Ethernet)	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter

BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC
Protocols	
• IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	100
Services	
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
 Number of connectable IO Devices, max. 	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Of which IO devices with IRT, max.	64
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8; in total across all interfaces
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
— PROFINET Security Class	1
Update time for IRT	
— for send cycle of 250 μs	250 µs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum
— for send cycle of 500 μs	update time of 500 µs of the isochronous OB is decisive 500 µs to 8 ms
·	1 ms to 16 ms
— for send cycle of 1 ms	
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— Isochronous mode — IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes .
 Number of IO Controllers with shared device, max. 	4
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
Interface	
Interface types	
• RS 485	Yes; Via CM DP module
• 10 405	4
Number of ports	1
Number of ports	Yes
Number of portsProtocolsPROFIBUS DP master	Yes
Number of ports Protocols	

 Number of connections, max. 	48; Of which 4 each reserved for ES and HMI
 max. number of DP devices 	125; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Candaga	PROFIDUS 01 PROFINE I
Services	Al-
— Equidistance	No
— Isochronous mode	No
— activation/deactivation of DP devices	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	40.40.47
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	128; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	88
 Number of connections per CP/CM 	32
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
MPD interconnection curported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
MRP interconnection, supported MRPD	Yes; Requirement: IRT
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	30
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
Data record routing	Yes
S7 communication, as server	Yes
S7 communication, as server S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	See offiline help (S7 confindincation, user data size)
TCP/IP	Yes
— Data length, max.	64 kbyte
— several passive connections per port, supported	Yes
ISO-on-TCP (RFC1006) Data length, max	Yes
— Data length, max.● UDP	64 kbyte
	Yes 2 khyte: 1 472 hytes for LIDP broadcast
— Data length, max.— UDP multicast	2 kbyte; 1 472 bytes for UDP broadcast
	Yes; max. 78 multicast circuits
• DHCP	Yes
DNS SNMP	Yes Yes
• SNMP • DCP	Yes
• DCP • LLDP	Yes
Encryption Web server.	Yes; Optional
Web server	Voc. Standard and upor pages
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	50
— Number of sessions, max.	50
 number of simultaneous HTTP calls, max. 	4

— HTTP request body, max. OPC UA	131 072 byte
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
 Number of connections, max. 	4
 Number of nodes of the client interfaces, recommended max. 	1 000
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_ max. 	
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
— Number of elements for one call of OPC_UA_MethodGetHandleList, max.	100
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
 Number of registerable nodes, max. 	5 000
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100
— Number of inputs/outputs when calling OPC_UA_MethodCall, max.	20
	(A&C), custom address space, role-based access control
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
_	
•	
	OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost
Number of monitored items, recommended max. Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the
 Number of nodes for user-defined server interfaces, max. 	15 000
Alarms and Conditions	Yes
Number of program alarms	100
	50
Further protocols	
• MODBUS	Yes; MODBUS TCP
7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	250
number of tags/attributes for subscriptions, max.	2 000
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
Number of program alarms	600
Number of alarms for system diagnostics	100
 Number of alarms for motion technology objects 	160
OPC_UA_MethodCall, max. OPC UA Server — Application authentication — Security policies — User authentication — GDS support (certificate management) — Number of sessions, max. — Number of accessible variables, max. — Number of registerable nodes, max. — Number of subscriptions per session, max. — Sampling interval, min. — Publishing interval, min. — Number of server methods, max. — Number of monitored items, recommended max. — Number of monitored items, recommended max. — Number of server interfaces, max. — Number of nodes for user-defined server interfaces, max. • Alarms and Conditions — Number of program alarms — Number of alarms for system diagnostics Further protocols • MODBUS 7 message functions Number of login stations for message functions, max. number of subscriptions, max. number of subscriptions, max. Program alarms Number of loadable program messages in RUN, max. Number of simultaneously active program alarms • Number of program alarms • Number of alarms for system diagnostics	Yes; data access (read, write, subscribe), method call, alarms & condition (A&C), custom address space, role-based access control Yes available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss "anonymous" or by user name & password Yes 32 50 000 10 000 50 100 ms 200 ms 20; max. 20 concurrently running jobs each for asynchronous instructions OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost 20 4 000; for 1 s sampling interval and 1 s send interval 10 of each "Server interfaces" / "Companion specification" type and 20 of tr type "Reference namespace" 15 000 Yes 100 50 Yes; MODBUS TCP 32 250 2 000 Yes 5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH 5 000 600 100

Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	Yes
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
Variables	
Number of variables, max.	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
of which status variables, max.	200: parioh
	200; per job
— of which control variables, max.	200; per job
Forcing	Voc
• Forcing	Yes
• Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	1 000
— of which powerfail-proof	500
Traces	
 Number of configurable Traces 	4
Memory size per trace, max.	512 kbyte
nterrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes
 Connection display LINK TX/RX 	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Number of available Motion Control resources for	
 Number of available Motion Control resources for technology objects 	program; selection guide via the TIA Selection Tool
 Number of available Motion Control resources for technology objects Required Motion Control resources 	program; selection guide via the TIA Selection Tool 1 120
 Number of available Motion Control resources for technology objects 	program; selection guide via the TIA Selection Tool
 Number of available Motion Control resources for technology objects Required Motion Control resources 	program; selection guide via the TIA Selection Tool 1 120
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis 	program; selection guide via the TIA Selection Tool 1 120 40 80 160
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis 	program; selection guide via the TIA Selection Tool 1 120 40 80
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis 	program; selection guide via the TIA Selection Tool 1 120 40 80 160
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per probe Positioning axis Number of positioning axes at motion control cycle 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40
 Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
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eq] — global warming potential, (after end of life cycle) [CO2 eq]	-0.949 kg
product functions / security / header	
PROFINET Security Class	1
signed firmware update	Yes
Secure Boot	Yes
safely removing data	Yes
Ambient conditions	
Ambient temperature during operation	
horizontal installation, min.	-30 °C; No condensation
horizontal installation, max.	60 °C
vertical installation, min.	-30 °C; No condensation
vertical installation, max.	50 °C
Altitude during operation relating to sea level	
Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	2 2 2 2 11, 200 manda
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— CFC	Yes
— GRAPH	Yes
Know-how protection	
User program protection/password protection	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
protection of confidential configuration data	Yes
Protection level: Write protection	Yes
Protection level: Read/write protection	Yes
Protection level: Write protection for Failsafe	No
Protection level: Complete protection	Yes
User administration	Yes; device-wide and centralized
Number of users	100
Number of groups	100
Number of roles	50
programming / cycle time monitoring / header	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	100 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	265 g
ννοιχτις, αρριολ.	200 g

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