



variable speed drive ATV61 - 630kW 900HP - 380...480V - IP20

ATV61HC63N4

! Discontinued on: 01-Jan-2025

① Discontinued

Main

Range of product	Altivar 61
Product or component type	Variable speed drive
Product specific application	Pumping and ventilation machine
Component name	ATV61
Motor power kW	560 kW, 3 phases at 380480 V 630 kW, 3 phases at 380480 V
Motor power hp	800 hp, 3 phases at 380480 V 900 hp, 3 phases at 380480 V
power supply voltage	380480 V - 1510 %
supply number of phases	3 phases
Line current	1091 A for 380 V 3 phases 630 kW / 900 hp 858 A for 480 V 3 phases 560 kW / 800 hp 964 A for 480 V 3 phases 630 kW / 900 hp 978 A for 380 V 3 phases 560 kW / 800 hp
EMC filter	Level 3 EMC filter
Assembly style	With heat sink
Apparent power	718 kVA at 380 V 3 phases 630 kW / 900 hp 643.6 kVA at 380 V 3 phases 560 kW / 800 hp
maximum prospective line Isc	50 kA for 3 phases
Maximum transient current	1425.6 A for 60 s, 3 phases
Nominal switching frequency	2.5 kHz
Switching frequency	28 kHz adjustable 2.58 kHz with derating factor
asynchronous motor control	Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio, 2 points Voltage/frequency ratio - Energy Saving, quadratic U/f
Synchronous motor control profile	Vector control without sensor, standard
Communication port protocol	Modbus CANopen
Type of polarization	No impedance for Modbus

Option card	Communication card for APOGEE FLN	
	Communication card for BACnet	
	Communication card for CC-Link	
	Controller inside programmable card	
	Communication card for DeviceNet	
	Communication card for EtherNet/IP	
	Communication card for Fipio	
	I/O extension card	
	Communication card for Interbus-S	
	Communication card for LonWorks	
	Communication card for METASYS N2	
	Communication card for Modbus Plus	
	Communication card for Modbus TCP	
	Communication card for Modbus/Uni-Telway	
	Multi-pump card	
	Communication card for Profibus DP	
	Communication card for Profibus DP V1	

Complementary

Product destination	Synchronous motors Asynchronous motors						
power supply voltage limits	323528 V						
power supply frequency	5060 Hz - 55 %						
power supply frequency limits	47.563 Hz						
Continuous output current	1188 A at 2.5 kHz, 380 V - 3 phases 1188 A at 2.5 kHz, 460 V - 3 phases						
Output frequency	0.1500 Hz						
Speed range	1100 in open-loop mode, without speed feedback						
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback						
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback						
Transient overtorque	130 % of nominal motor torque +/- 10 % for 60 s						
Braking torque	<= 125 % with braking resistor 30 % without braking resistor						
Regulation loop	Frequency PI regulator						
Motor slip compensation	Can be suppressed Not available in voltage/frequency ratio (2 or 5 points) Adjustable Automatic whatever the load						
diagnostic	1 LED (red) for drive voltage						
Output voltage	<= power supply voltage						
electrical isolation	Between power and control terminals						
type of cable for mounting in an enclosure	With an IP21 or an IP31 kit: 3 wire(s)IEC cable at 40 °C, copper 70 °C / PVC With UL Type 1 kit: 3 wire(s)UL 508 cable at 40 °C, copper 75 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 70 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 90 °C / XLPE/EPR						
Electrical connection	Terminal 2.5 mm² / AWG 14 (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR) Terminal 8 x 185 mm² / 5 x 500 kcmil (PC/-, PO, PA/+) Terminal 2 x 4 x 185 mm² / 2 x 3 x 500 kcmil (R/L1.1, S/L2.1, T/L3.1, R/L1.2, S/L2.2, T/L3.2) Terminal 6 x 185 mm² / 5 x 500 kcmil (U/T1, V/T2, W/T3)						
Tightening torque	0.6 N.m (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR) 41 N.m, 360 lb.in (PC/-, PO, PA/+) 41 N.m, 360 lb.in (R/L1.1, S/L2.1, T/L3.1, R/L1.2, S/L2.2, T/L3.2) 41 N.m, 360 lb.in (U/T1, V/T2, W/T3)						

Supply	Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC, +/- 5 %, <10 mA with overload and short-circuit protection Internal supply: 24 V DC (2127 V), <200 mA with overload and short-circuit					
	protection External supply: 24 V DC (1930 V)					
Analogue input number	2					
Analogue input type	Al1-/Al1+ bipolar differential voltage: +/- 10 V DC 24 V max, resolution 11 bits + sign Al2 software-configurable current: 020 mA, impedance: 242 Ohm, resolution 11 bits Al2 software-configurable voltage: 010 V DC 24 V max, impedance: 30000 Ohm, resolution 11 bits					
sampling time	2 ms +/- 0.5 ms (Al1-/Al1+) - analog input 2 ms +/- 0.5 ms (Al2) - analog input 2 ms +/- 0.5 ms (AO1) - analog output 2 ms +/- 0.5 ms (Ll1Ll5) - discrete input 2 ms +/- 0.5 ms (Ll6)if configured as logic input - discrete input					
absolute accuracy precision	+/- 0.6 % (Al1-/Al1+) for a temperature variation 60 °C +/- 0.6 % (Al2) for a temperature variation 60 °C +/- 1 % (AO1) for a temperature variation 60 °C					
inearity error	+/- 0.15 % of maximum value (Al1-/Al1+) +/- 0.15 % of maximum value (Al2) +/- 0.2 % (AO1)					
Analogue output number	1					
Analogue output type	AO1 software-configurable current, analogue output range 020 mA, impedance: 500 Ohm, resolution 10 bits AO1 software-configurable voltage, analogue output range 010 V DC, impedance: 470 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V, 20 mA					
Discrete output number	2					
Discrete output type	Configurable relay logic: (R1A, R1B, R1C) NO/NC - 100000 cycles Configurable relay logic: (R2A, R2B) NO - 100000 cycles					
naximum response time	<= 100 ms in STO (Safe Torque Off) R1A, R1B, R1C <= 7 ms, tolerance +/- 0.5 ms R2A, R2B <= 7 ms, tolerance +/- 0.5 ms					
Minimum switching current	3 mA at 24 V DC for configurable relay logic					
Maximum switching current	R1, R2: 2 A at 250 V AC inductive load, cos phi = 0.4 and L/R = 7 ms R1, R2: 2 A at 30 V DC inductive load, cos phi = 0.4 and L/R = 7 ms R1, R2: 5 A at 250 V AC resistive load, cos phi = 1 and L/R = 0 ms R1, R2: 5 A at 30 V DC resistive load, cos phi = 1 and L/R = 0 ms					
Discrete input number	7					
Discrete input type	Programmable (LI1LI5)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm Switch-configurable (LI6)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm Switch-configurable PTC probe (LI6)06 probes - 1500 Ohm Safety input (PWR)24 V DC (<= 30 V) - 1500 Ohm					
Discrete input logic	Negative logic (sink) (LI1LI5), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (LI1LI5), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (LI6)if configured as logic input, > 16 V (state 0), < 10 V (state 1) Positive logic (source) (LI6)if configured as logic input, < 5 V (state 0), > 11 V (state 1)					
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.01 to 9000 s Automatic adaptation of ramp if braking capacity exceeded, by using resistor					
Braking to standstill	By DC injection					

Protection type	Against exceeding limit speed: drive
	Against input phase loss: drive
	Break on the control circuit: drive
	Input phase breaks: drive
	Line supply overvoltage: drive
	Line supply undervoltage: drive
	Overcurrent between output phases and earth: drive
	Overheating protection: drive
	Overvoltages on the DC bus: drive
	Power removal: drive
	Short-circuit between motor phases: drive
	Thermal protection: drive
	Motor phase break: motor
	Power removal: motor
	Thermal protection: motor
Insulation resistance	> 1 mOhm 500 V DC for 1 minute to earth
Frequency resolution	Analog input: 0.024/50 Hz
	Display unit: 0.1 Hz
Connector type	1 RJ45 (on front face) for Modbus
	1 RJ45 (on terminal) for Modbus
	Male SUB-D 9 on RJ45 for CANopen
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal
	9600 bps, 19200 bps for Modbus on front face
	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen
Data format	8 bits, 1 stop, even parity for Modbus on front face
	8 bits, odd even or no configurable parity for Modbus on terminal
Number of addresses	1127 for CANopen
	1247 for Modbus
Method of access	Slave CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Net weight	435 kg
Width	1120 mm
Height	1390 mm
Depth	377 mm

Environment

Noise level	71 dB conforming to 86/188/EEC					
Dielectric strength	3535 V DC between earth and power terminals 5092 V DC between control and power terminals					
Electromagnetic compatibility	Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11					
Standards	EN/IEC 61800-3 EN 61800-3 environments 1 category C3 IEC 60721-3-3 class 3C2 UL Type 1 EN 55011 class A group 2 EN/IEC 61800-5-1 EN 61800-3 environments 2 category C3					

Product certifications	UL
	GOST
	DNV
	CSA
	C-Tick
	NOM 117
Pollution degree	3 conforming to EN/IEC 61800-5-1
	3 conforming to UL 840
degree of proctection	IP41 on upper part conforming to EN/IEC 60529
	IP41 on upper part conforming to EN/IEC 61800-5-1
	IP00 conforming to EN/IEC 60529
	IP00 conforming to EN/IEC 61800-5-1
	IP30 on side parts conforming to EN/IEC 60529
	IP30 on side parts conforming to EN/IEC 61800-5-1
	IP30 on the front panel conforming to EN/IEC 60529
	IP30 on the front panel conforming to EN/IEC 61800-5-1
Vibration resistance	0.6 gn (f= 10200 Hz) conforming to EN/IEC 60068-2-6
	1.5 mm peak to peak (f= 310 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	4 gn for 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	595 % without condensation conforming to IEC 60068-2-3
	595 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for	-1045 °C (without derating)
operation	4560 °C (with derating factor)
Ambient air temperature for storage	-2570 °C
Operating altitude	<= 1000 m without derating
	10003000 m with current derating 1 % per 100 m

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	53.0 cm
Package 1 Width	117.0 cm
Package 1 Length	145.0 cm
Package 1 Weight	475.0 kg

Contractual warranty

Warranty 18 months



Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing "Use Better, Use Longer, Use Again" campaign to extend product lifetimes and recyclability.

Environmental Data explained >

How we assess product sustainability >

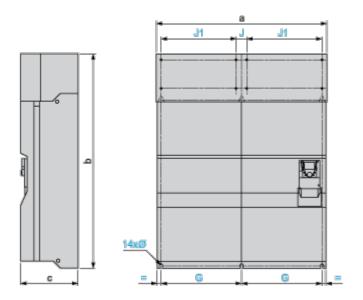
Use Better

EU RoHS Directive Pro-active compliance (Product out of EU RoHS legal scope)						
Use Again						
○ Repack and remanufacture						
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins					

Dimensions Drawings

UL Type 1/IP 20 Drives

Dimensions with or without 1 Option Card (1)



Dimensions in mm

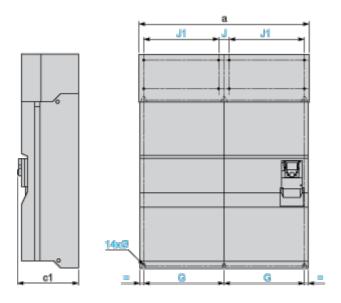
а	b	С	G	J	J1	Н	K	K1	K2	Ø
1120	1390	377	532.5	75	495	1120	150	75	30	11.5

Dimensions in in.

а	b	С	G	J	J1	Н	K	K1	K2	Ø
44.09	54.72	14.84	20.96	2.95	19.49	44.09	5.90	2.95	1.18	0.45

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Dimensions with 2 Option Cards (1)



Dimensions in mm

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а	с1	G	J	J1	Н	K	K1	K2	Ø
1120	392	532.5	75	495	1120	150	75	30	11.5

Dimensions in in.

а	c1	G	J	J1	Н	K	K1	K2	Ø
44.09	15.43	20.96	2.95	19.49	44.09	5.90	2.95	1.18	0.45

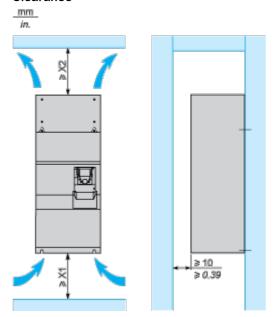
(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

ATV61HC63N4

Mounting and Clearance

Mounting Recommendations

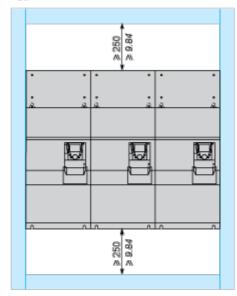
Clearance

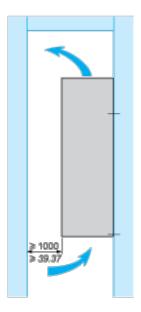


X1 in mm	X2 in mm	X1 in in.	X2 in in.
250	400	9.84	15.75

These drives can be mounted side by side, observing the following mounting recommendations:







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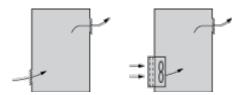
Specific Recommendations for Mounting the Drive in an Enclosure

Ventilation

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To ensure proper air circulation in the drive:

- . Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

Dust and Damp Proof Metal Enclosure (IP 54)

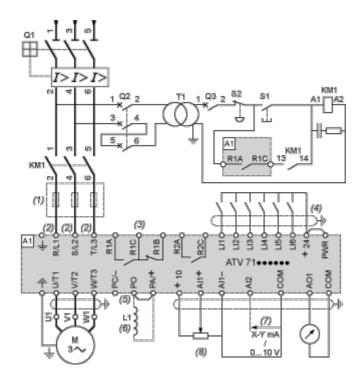
The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor



A1 ATV61 drive

KM1 Contactor

L1 DC choke

Q1 Circuit-breaker

Q2 GV2 L rated at twice the nominal primary current of T1

Q3 GB2CB05

S1, S2 XB4 B or XB5 A pushbuttons

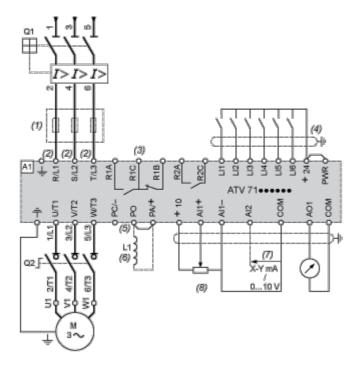
T1 100 VA transformer 220 V secondary

- (1) Line choke (three-phase); mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

Product datasheet ATV61HC63N4

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

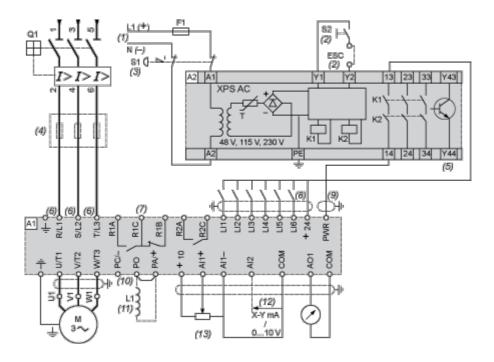
Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



- A1 ATV61 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user quide).
- (5) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



A1 ATV61 drive

A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.

- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (11) Optional DC choke for ATV61H••••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X,

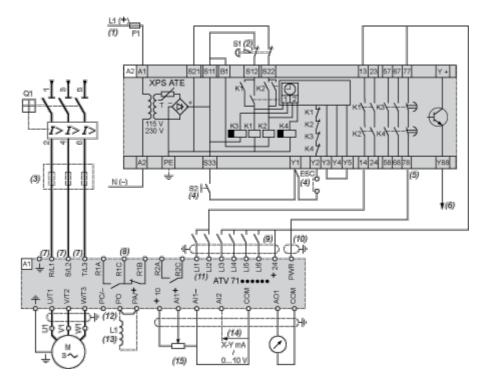
ATV61HC63N4

ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine



A1 ATV61 drive

A2 (5) Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.

F1 Fuse

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- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) The logic output can be used to signal that the machine is in a safe state.
- (6) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (7) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.

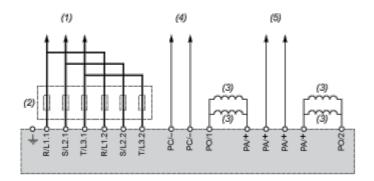
ATV61HC63N4

- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12) There is no PO terminal on ATV61HC11Y...HC80Y drives.
- (13) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

17-Apr-2025

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Power Terminal Connections



- (1) To circuit-breaker.
- (2) Line chokes, these are mandatory for ATV61HC50Y...HC80Y drives, to be ordered separately.
- (3) DC chokes supplied as standard with ATV61HC50N4, HC63N4 drives. Not available for ATV61HC50Y...HC80Y.
- (4) To DC bus -
- (5) To DC bus +

ATV61HC63N4

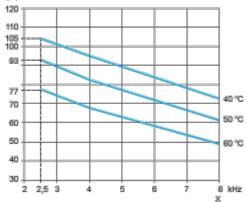
Performance Curves

Derating Curves

The derating curves for the drive nominal current (In) depend on the temperature and the switching frequency. For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.

Drive combined with a 560 kW motor

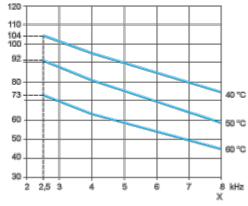
L/ In (%)



Switching frequency

Drive combined with a 630 kW motor





Switching frequency